

PDE per modelli a volatilità meccanica:

$$\frac{\partial F}{\partial t} + rS \frac{\partial F}{\partial S} + \alpha \frac{\partial F}{\partial v} + \frac{\sigma^2}{2} v \frac{\partial^2 F}{\partial S^2} + S \rho \sigma \sqrt{v} \frac{\partial^2 F}{\partial S \partial v} +$$

$$+ \frac{\partial^2 F}{\partial v^2} \frac{\beta^2}{2} - rF = \Delta(t, S, v) \frac{\partial F}{\partial v}$$

(HESTON)

$$\Rightarrow \frac{\partial F}{\partial t} + rS \frac{\partial F}{\partial S} + k(\theta - v) \frac{\partial F}{\partial v} + \frac{\sigma^2}{2} v \frac{\partial^2 F}{\partial S^2} +$$

$$+ S \rho \sigma \sqrt{v} \frac{\partial^2 F}{\partial S \partial v} + \frac{\sigma^2}{2} v \frac{\partial^2 F}{\partial v^2} - rF = \Delta v \frac{\partial F}{\partial v}$$

$$\Rightarrow \frac{\partial F}{\partial t} + rS \frac{\partial F}{\partial S} + [k(\theta - v) - \Delta v] \frac{\partial F}{\partial v} + \frac{\sigma^2}{2} v \frac{\partial^2 F}{\partial S^2} +$$

$$+ S \rho \sigma \sqrt{v} \frac{\partial^2 F}{\partial S \partial v} + \frac{\sigma^2}{2} v \frac{\partial^2 F}{\partial v^2} - rF = 0$$

con le seguenti boundary conditions:

$$\left\{ \begin{array}{l} F(T, S, v) = \phi(S_T) \quad (\text{e.g., call option} \rightarrow \max\{S_T - k, 0\}) \\ F(t, 0, v) = 0 \\ \frac{\partial F(t, \infty, v)}{\partial S} = 1 \\ F(t, S, \infty) = S \end{array} \right.$$

Per comodità, poniamo  $x = l u(S)$  e risolviamo la PDE:

$$\frac{\partial F}{\partial S} = \frac{\partial F}{\partial x} \frac{\partial x}{\partial S} = \frac{\partial F}{\partial x} \frac{1}{S}$$

$$\frac{\partial^2 F}{\partial S^2} = \frac{\partial}{\partial S} \left( \frac{\partial F}{\partial S} \right) = \frac{\partial}{\partial S} \left( \frac{\partial F}{\partial x} \cdot \frac{1}{S} \right) = \frac{\partial}{\partial S} \left( \frac{\partial F}{\partial x} \right) \cdot \frac{1}{S} +$$

$$+ \frac{\partial F}{\partial x} \left( -\frac{1}{S^2} \right) = \frac{\partial}{\partial x} \left( \frac{\partial F}{\partial S} \right) \cdot \frac{1}{S} - \frac{1}{S^2} \frac{\partial F}{\partial x}$$

$$= \frac{1}{S} \frac{\partial}{\partial x} \left( \frac{\partial F}{\partial x} \cdot \frac{1}{S} \right) - \frac{1}{S^2} \frac{\partial F}{\partial x}$$

$$= \frac{1}{S^2} \frac{\partial^2 F}{\partial x^2} - \frac{1}{S^2} \frac{\partial F}{\partial x} = \frac{1}{S^2} \left( \frac{\partial^2 F}{\partial x^2} - \frac{\partial F}{\partial x} \right)$$

$$\frac{\partial^2 F}{\partial S \partial V} = \frac{\partial}{\partial V} \left( \frac{\partial F}{\partial S} \right) = \frac{\partial}{\partial V} \left( \frac{\partial F}{\partial x} \cdot \frac{1}{S} \right) = \frac{\partial^2 F}{\partial x \partial V} \cdot \frac{1}{S}$$

⇒ Risolviamo la PDE:

$$\frac{\partial F}{\partial t} + \pi S \frac{\partial F}{\partial x} \cdot \frac{1}{S} + [k(\theta - v) - \Delta v] \frac{\partial F}{\partial V} + \frac{\sigma^2}{2} v \frac{1}{S^2} \left( \frac{\partial^2 F}{\partial x^2} - \frac{\partial F}{\partial x} \right) -$$

$$+ \rho \sigma v \frac{1}{S} \frac{\partial^2 F}{\partial x \partial V} + \frac{\sigma^2 v}{2} \frac{\partial^2 F}{\partial V^2} - \pi F = 0$$

$$\Rightarrow \frac{\partial F}{\partial t} + \pi \frac{\partial F}{\partial x} + [k(\theta - v) - \Delta v] \frac{\partial F}{\partial V} + \frac{v}{2} \left( \frac{\partial^2 F}{\partial x^2} - \frac{\partial F}{\partial x} \right) +$$

$$+ \rho \sigma v \frac{\partial^2 F}{\partial x \partial V} + \frac{\sigma^2 v}{2} \frac{\partial^2 F}{\partial V^2} - \pi F = 0$$

$$\Rightarrow \frac{\partial F}{\partial t} + \left( r - \frac{v}{2} \right) \frac{\partial F}{\partial x} + \left[ k(\theta - v) - \Delta v \right] \frac{\partial F}{\partial v} + \frac{v}{2} \frac{\partial^2 F}{\partial x^2} + \textcircled{84}$$

$$+ \frac{\sigma^2 v}{2} \frac{\partial^2 F}{\partial v^2} + \rho \sigma v \frac{\partial^2 F}{\partial x \partial v} - rF = 0, \quad \forall F \quad (F - PDE)$$

Questo ~~PDE~~ vale anche per un'opzione call, per la quale si ha

$$C_t = S_t P_1 - R e^{-r(T-t)} P_2 = e^{rx} P_1 - R e^{-r(T-t)} P_2$$

(STRIKE PRICE)

⇒ Allora, si ha:

$$\frac{\partial C}{\partial t} = e^{rx} \frac{\partial P_1}{\partial t} - R e^{-r(T-t)} \frac{\partial P_2}{\partial t} - R r e^{-r(T-t)} P_2$$

$$= e^{rx} \frac{\partial P_1}{\partial t} - R e^{-r(T-t)} \left[ r P_2 + \frac{\partial P_2}{\partial t} \right]$$

$$\frac{\partial C}{\partial x} = e^{rx} P_1 + e^{rx} \frac{\partial P_1}{\partial x} - R e^{-r(T-t)} \frac{\partial P_2}{\partial x}$$

$$\frac{\partial^2 C}{\partial x^2} = e^{rx} P_1 + e^{rx} \frac{\partial P_1}{\partial x} + e^{rx} \frac{\partial P_1}{\partial x} + e^{rx} \frac{\partial^2 P_1}{\partial x^2} - R e^{-r(T-t)} \frac{\partial^2 P_2}{\partial x^2}$$

$$= e^{rx} \left[ P_1 + 2 \frac{\partial P_1}{\partial x} + \frac{\partial^2 P_1}{\partial x^2} \right] - R e^{-r(T-t)} \frac{\partial^2 P_2}{\partial x^2}$$

$$\frac{\partial C}{\partial v} = e^{rx} \frac{\partial P_1}{\partial v} - R e^{-r(T-t)} \frac{\partial P_2}{\partial v}$$

$$\frac{\partial^2 C}{\partial v^2} = e^x \frac{\partial^2 P_1}{\partial v^2} - R e^{-\pi(\tau-t)} \frac{\partial^2 P_2}{\partial v^2}$$

$$\frac{\partial^2 C}{\partial x \partial v} = e^x \frac{\partial P_1}{\partial v} + e^x \frac{\partial^2 P_1}{\partial x \partial v} - R e^{-\pi(\tau-t)} \frac{\partial^2 P_2}{\partial x \partial v}$$

Sostituendo in (F-PDE), si ha

$$\begin{aligned}
 & e^x \frac{\partial P_1}{\partial t} - R e^{-\pi(\tau-t)} \left[ r P_2 + \frac{\partial P_2}{\partial t} \right] + \left( \pi - \frac{v}{2} \right) \left[ e^x P_1 + e^x \frac{\partial P_1}{\partial x} + R e^{-\pi(\tau-t)} \frac{\partial C}{\partial v} \right] \\
 & + \left[ k(\theta - v) - \lambda v \right] \left[ e^x \frac{\partial P_1}{\partial v} - R e^{-\pi(\tau-t)} \frac{\partial P_2}{\partial v} \right] + \\
 & + \frac{v}{2} \left[ e^x \left( P_1 + 2 \frac{\partial P_1}{\partial x} + \frac{\partial^2 P_1}{\partial x^2} \right) - R e^{-\pi(\tau-t)} \frac{\partial^2 P_2}{\partial x^2} \right] + \\
 & + \frac{\sigma^2 v}{2} \left[ e^x \frac{\partial^2 P_1}{\partial v^2} - R e^{-\pi(\tau-t)} \frac{\partial^2 P_2}{\partial v^2} \right] + \\
 & + \rho \sigma v \left[ e^x \frac{\partial P_1}{\partial v} + e^x \frac{\partial^2 P_1}{\partial x \partial v} - R e^{-\pi(\tau-t)} \frac{\partial^2 P_2}{\partial x \partial v} \right] + \\
 & - r \left[ e^x P_1 - R e^{-\pi(\tau-t)} P_2 \right] = 0
 \end{aligned}$$

Raccogliamo a fattori comuni:

$$e^{\alpha} \left[ \frac{\partial P_1}{\partial t} + \left( \pi - \frac{v}{2} \right) \frac{\partial P_1}{\partial x} + \left[ k(\theta - v) - \Delta v \right] \frac{\partial P_1}{\partial v} + v \frac{\partial P_1}{\partial x} + \frac{v}{2} \frac{\partial^2 P_1}{\partial x^2} + \frac{\sigma^2 v}{2} \frac{\partial^2 P_1}{\partial v^2} + \rho \sigma v \frac{\partial^2 P_1}{\partial x \partial v} \right] + \rho \sigma v \frac{\partial P_1}{\partial v} \Bigg] +$$

$$- R e^{-\pi(\tau-t)} \left[ \frac{\partial P_2}{\partial t} + \left( \pi - \frac{v}{2} \right) \frac{\partial P_2}{\partial x} + \left[ k(\theta - v) - \Delta v \right] \frac{\partial P_2}{\partial v} + \frac{v}{2} \frac{\partial^2 P_2}{\partial x^2} + \frac{\sigma^2 v}{2} \frac{\partial^2 P_2}{\partial v^2} + \rho \sigma v \frac{\partial^2 P_2}{\partial x \partial v} \right] = 0$$

$$\Rightarrow \left\{ \begin{aligned} & \frac{\partial P_1}{\partial t} + \left( \pi + \frac{v}{2} \right) \frac{\partial P_1}{\partial x} + \left[ \cancel{k(\theta - v) - \Delta v + \rho \sigma v} \right] \frac{\partial P_1}{\partial v} + \frac{v}{2} \frac{\partial^2 P_1}{\partial x^2} + \\ & + \frac{\sigma^2 v}{2} \frac{\partial^2 P_1}{\partial v^2} + \rho \sigma v \frac{\partial^2 P_1}{\partial x \partial v} = 0 \\ & \frac{\partial P_2}{\partial t} + \left( \pi - \frac{v}{2} \right) \frac{\partial P_2}{\partial x} + \left[ k(\theta - v) - \Delta v \right] \frac{\partial P_2}{\partial v} + \frac{v}{2} \frac{\partial^2 P_2}{\partial x^2} + \\ & + \frac{\sigma^2 v}{2} \frac{\partial^2 P_2}{\partial v^2} + \rho \sigma v \frac{\partial^2 P_2}{\partial x \partial v} = 0 \end{aligned} \right.$$

In forma compatta:

$$\left\{ \begin{aligned} & \frac{\partial P_i}{\partial t} + (\pi + u_i v) \frac{\partial P_i}{\partial x} + (a - b_i v) \frac{\partial P_i}{\partial v} + \frac{v}{2} \frac{\partial^2 P_i}{\partial x^2} + \\ & + \frac{\sigma^2 v}{2} \frac{\partial^2 P_i}{\partial v^2} + \rho \sigma v \frac{\partial^2 P_i}{\partial x \partial v} = 0, \quad \forall i=1,2 \quad (*) \\ & u_1 = \frac{1}{2}, \quad u_2 = -\frac{1}{2}, \quad a = k\theta, \quad b_1 = k + \Delta - \rho\sigma, \quad b_2 = k + \Delta \end{aligned} \right.$$

RECAU:  $P_j = \frac{1}{2} + \frac{1}{2\pi} \int_0^{+\infty} \operatorname{Re} \left[ \frac{e^{-iux} f_j(u; x, v)}{iu} \right] du, \quad j=1,2$  (8)

$\Rightarrow$  portiamo esplicitare la funzione caratteristica?

$\Rightarrow$  Sì, attraverso le PDE associate a  $P_j, j=1,2$

GUESS & VERIFY APPROACH:

(\*\*)  $f_j(u; x, v) = \exp\{C_j(\tau, u) + D_j(\tau, u)v + iux\}, \quad \tau := T-t$

$\Rightarrow$  vogliamo determinare  $C_j, D_j, j=1,2$ .

(PDE in (\*\*))  $\Rightarrow$

$$-\frac{\partial f_j}{\partial \tau} + (\pi + u_2 v) \frac{\partial f_j}{\partial x} + (a - b_2 v) \frac{\partial f_j}{\partial v} + \frac{1}{2} v \frac{\partial^2 f_j}{\partial x^2} + \frac{1}{2} \sigma^2 v \frac{\partial^2 f_j}{\partial v^2} + \rho \sigma v \frac{\partial^2 f_j}{\partial x \partial v} = 0$$

$\tau = T-t \Leftrightarrow t = T-\tau \Rightarrow \frac{\partial F}{\partial \tau} = -1$

$\frac{\partial F}{\partial \tau} = \frac{\partial F}{\partial \tau} \frac{\partial \tau}{\partial \tau}, \quad \frac{\partial F}{\partial \tau} = -\frac{\partial F}{\partial \tau}$

Solviamo le derivate, tenendo conto dell'ipotesi (\*\*):

$$\frac{\partial f_{\dot{\alpha}}}{\partial \tau} = \underbrace{(\dot{C}_{\dot{\alpha}} + \dot{D}_{\dot{\alpha}} v)}_{f_{\dot{\alpha}}} \exp\{C_{\dot{\alpha}} + D_{\dot{\alpha}} v + i u x\}$$

$$\frac{\partial f_{\dot{\alpha}}}{\partial x} = i u \underbrace{\exp\{C_{\dot{\alpha}} + D_{\dot{\alpha}} v + i u x\}}_{f_{\dot{\alpha}}}$$

$$\frac{\partial^2 f_{\dot{\alpha}}}{\partial x^2} = -u^2 \underbrace{\exp\{C_{\dot{\alpha}} + D_{\dot{\alpha}} v + i u x\}}_{f_{\dot{\alpha}}}$$

$$\frac{\partial f_{\dot{\alpha}}}{\partial v} = \underbrace{D_{\dot{\alpha}} \exp\{C_{\dot{\alpha}} + D_{\dot{\alpha}} v + i u x\}}_{f_{\dot{\alpha}}}$$

$$\frac{\partial^2 f_{\dot{\alpha}}}{\partial v^2} = \underbrace{D_{\dot{\alpha}}^2 \exp\{C_{\dot{\alpha}} + D_{\dot{\alpha}} v + i u x\}}_{f_{\dot{\alpha}}}$$

$$\frac{\partial^2 f_{\dot{\alpha}}}{\partial x \partial v} = i u \underbrace{D_{\dot{\alpha}} \exp\{C_{\dot{\alpha}} + D_{\dot{\alpha}} v + i u x\}}_{f_{\dot{\alpha}}}$$

Dunque:

$$- (\dot{C}_{\dot{\alpha}} + \dot{D}_{\dot{\alpha}} v) f_{\dot{\alpha}} + (u + u_{\dot{\alpha}} v) f_{\dot{\alpha}} i u + (a - b_{\dot{\alpha}} v) D_{\dot{\alpha}} f_{\dot{\alpha}} + \frac{1}{2} v (-u^2) f_{\dot{\alpha}} + \frac{1}{2} \sigma^2 v D_{\dot{\alpha}}^2 f_{\dot{\alpha}} + \rho \sigma v i u D_{\dot{\alpha}} f_{\dot{\alpha}} = 0, \quad \forall \dot{\alpha} = 1, 2$$

$$\Rightarrow \left[ -\dot{C}_{\dot{\alpha}} + i u u + a D_{\dot{\alpha}} \right] + \left[ -\dot{D}_{\dot{\alpha}} + u_{\dot{\alpha}} i u - b_{\dot{\alpha}} D_{\dot{\alpha}} + \frac{-u^2}{2} + \frac{1}{2} \sigma^2 D_{\dot{\alpha}}^2 + \rho \sigma i u D_{\dot{\alpha}} \right] v = 0, \quad \forall \dot{\alpha} = 1, 2$$

$$\Rightarrow \begin{cases} -\dot{C}_j + iur + a D_j = 0 \\ -\dot{D}_j + iu \cdot u_j - b_j D_j - \frac{1}{2} u^2 + \frac{1}{2} \sigma^2 D_j^2 + \\ + p \sigma i u D_j = 0 \end{cases}$$

con  $C_j(0, u) = D_j(0, u) = 0, \forall j=1,2$

Risolviemo le due ODEs.

ODE per  $D_j$ :

$$\dot{D}_j = \frac{\sigma^2}{2} D_j^2 + \underbrace{[p \sigma i u - b_j]}_{=: \alpha_j} D_j - \underbrace{\left[ \frac{1}{2} u^2 - i u \cdot u_j \right]}_{=: \Psi_j}$$

↳ ODE di Riccati

$D_j = -\frac{2}{\sigma^2} \frac{y'}{y}$ , dove  $y=y(r)$  definita come nel modello CIR

$$\Rightarrow \dot{D}_j = -\frac{2}{\sigma^2} \frac{y'' \cdot y - (y')^2}{y^2}$$

$$\Rightarrow -\frac{2}{\sigma^2} \frac{y''}{y} + \frac{2}{\sigma^2} \frac{(y')^2}{y^2} = \frac{2}{\sigma^2} \cdot \frac{y^2}{\sigma^2} \frac{(y')^2}{y^2} + \alpha \left( -\frac{2}{\sigma^2} \frac{y'}{y} \right) + \Psi_j$$

$$\Rightarrow +\frac{2}{\sigma^2} \frac{y''}{y} = +\frac{2\alpha_j}{\sigma^2} \frac{y'}{y} + \Psi_j$$

$$\Rightarrow \frac{y''}{y} = \frac{\alpha_j y'}{y} + \frac{\sigma^2}{2} \Psi_j$$

$$\Rightarrow y'' - \alpha_j y' - \frac{\sigma^2}{2} \Psi_j y = 0$$



Sol:  $y = C_1 e^{\lambda_1 \tilde{v}} + C_2 e^{\lambda_2 \tilde{v}}$

$$\Rightarrow y' = C_1 \lambda_1 e^{\lambda_1 \tilde{v}} + C_2 \lambda_2 e^{\lambda_2 \tilde{v}}$$

Imponiamo,  $y = e^{\lambda \tilde{v}} \Rightarrow \lambda^2 - \alpha \lambda - \frac{\sigma^2 \gamma}{2} = 0$

$$\Rightarrow \lambda = \frac{\alpha_j \pm \sqrt{\alpha_j^2 + 2\sigma^2 \gamma_j}}{2} = \frac{\alpha_j \pm d_j}{2},$$

essendo  $d_j = \sqrt{\alpha_j^2 + 2\sigma^2 \gamma_j}$

$$\Rightarrow d_j^2 = \alpha_j^2 + 2\sigma^2 \gamma_j$$

$$\Rightarrow d_j^2 - \alpha_j^2 = 2\sigma^2 \gamma_j$$

Allora, si ha:

$$D_j(\tilde{v}) = -\frac{2}{\sigma^2} \frac{C_1 \lambda_1 e^{\lambda_1 \tilde{v}} + C_2 \lambda_2 e^{\lambda_2 \tilde{v}}}{C_1 e^{\lambda_1 \tilde{v}} + C_2 e^{\lambda_2 \tilde{v}}}, \text{ con}$$

$$D_j(0) = -\frac{2}{\sigma^2} \frac{C_1 \lambda_1 + C_2 \lambda_2}{C_1 + C_2} = 0 \Rightarrow (C_1 + C_2) C_1 = -\frac{\lambda_2}{\lambda_1} C_2$$

$$\Rightarrow D_j = -\frac{2}{\sigma^2} \frac{\frac{-\lambda_2 C_2 \lambda_1}{\lambda_1} e^{\lambda_1 \tilde{v}} + C_2 \lambda_2 e^{\lambda_2 \tilde{v}}}{-\frac{\lambda_2 C_2}{\lambda_1} e^{\lambda_1 \tilde{v}} + C_2 e^{\lambda_2 \tilde{v}}}$$

$$= -\frac{2}{\sigma^2} \frac{-\lambda_1 \lambda_2 C_2 e^{\lambda_1 \tilde{v}} + C_2 \lambda_1 \lambda_2 e^{\lambda_2 \tilde{v}}}{-\lambda_2 C_2 e^{\lambda_1 \tilde{v}} + C_2 \lambda_1 e^{\lambda_2 \tilde{v}}}$$

$$= -\frac{2}{\sigma^2} \frac{x_1 x_2 (1 - e^{(x_2 - x_1)\tau})}{x_2 - x_1 e^{(x_2 - x_1)\tau}}$$

$$= -\frac{2}{\sigma^2} \frac{x_1 x_2 (1 - e^{(x_2 - x_1)\tau})}{x_2 - x_1 e^{(x_2 - x_1)\tau}}$$

$$= -\frac{2}{\sigma^2} \frac{\frac{d_j - d_j^2}{4} (1 - e^{d_j \tau})}{\frac{d_j + d_j}{2} - \frac{d_j - d_j}{2} e^{d_j \tau}}$$

~~$$= + \frac{2\gamma}{\sigma^2} \frac{(1 - e^{d\tau})}{(d+d) - (d-d)e^{d\tau}} = \frac{2\gamma (1 - e^{d\tau})}{(d-d) + 2d - (d-d)e^{d\tau}}$$~~

~~$$\Rightarrow D_j = \frac{2\gamma (1 - e^{d\tau})}{2d + (d-d)(1 - e^{d\tau})}$$~~

$$\Rightarrow D_j = -\frac{2}{\sigma^2} \frac{d_j - d_j^2}{(d_j + d_j) \left(1 - \frac{d_j - d_j}{d_j + d_j} e^{d_j \tau}\right)} (1 - e^{d_j \tau})$$

$$\Rightarrow D_j = \frac{d_j - d_j^2}{\sigma^2} \frac{1 - e^{d_j \tau}}{1 - q_j e^{d_j \tau}} = \frac{d_j + b_j - i \mu \sigma}{\sigma^2} \frac{1 - e^{d_j \tau}}{1 - q_j e^{d_j \tau}}$$

$$\dot{C}_j(r) = iur + a D_j(r)$$

$$\Rightarrow \int_0^{\tilde{r}} \dot{C}_j(s) ds = \int_0^{\tilde{r}} \left( iur + \frac{ar}{\sigma^2} \frac{1 - e^{d_j s}}{1 - q_j e^{d_j s}} \right) ds$$

$$\Rightarrow C_j(\tilde{r}) - C_j(0) = iur\tilde{r} + \frac{ar}{\sigma^2} \underbrace{\int_0^{\tilde{r}} \frac{1 - e^{d_j s}}{1 - q_j e^{d_j s}} ds}_{=: I}$$

Risolviemo I:

$$e^{d_j s} =: z \Rightarrow s = \frac{1}{d_j} \ln(z) \Rightarrow ds = \frac{1}{d_j} \frac{1}{z} dz$$

$$\begin{aligned} s=0 &\rightarrow z=1 \\ s=\tilde{r} &\rightarrow z=e^{d_j \tilde{r}} \end{aligned}$$

$$\Rightarrow I = \frac{1}{d_j} \int_1^{e^{d_j \tilde{r}}} \frac{1-z}{(1-q_j z)z} dz$$

NOTA: Cerchiamo F, G t.c.  $\frac{1-z}{z(1-q_j z)} = \frac{F}{z} + \frac{G}{1-q_j z}$

$$\Rightarrow 1-z = F(1-q_j z) + z \cdot G \Rightarrow 1-z = F + (G-F \cdot q_j)z$$

$$\Rightarrow \begin{cases} F=1 \\ G-F \cdot q_j = -1 \end{cases} \Rightarrow \begin{cases} F=1 \\ G=q_j-1 \end{cases}$$

$$\Rightarrow I = \frac{1}{d_j} \int_1^{\exp\{d_j \tau\}} \left( \frac{1}{z} - \frac{1 - q_j}{1 - q_j z} \right) dz$$

$$= \frac{1}{d_j} \ln(z) \Big|_1^{\exp\{d_j \tau\}} - \frac{1}{d_j} \int_1^{\exp\{d_j \tau\}} \frac{dz}{1 - q_j z} + \frac{q_j}{d_j} \int_1^{\exp\{d_j \tau\}} \frac{dz}{1 - q_j z}$$

$$= \frac{1}{d_j} \left[ \ln(\exp\{d_j \tau\}) - \ln(1) \right] + \frac{1}{d_j q_j} \int_1^{\exp\{d_j \tau\}} \frac{-q_j dz}{1 - q_j z} - \frac{1}{d_j} \int_1^{\exp\{d_j \tau\}} \frac{-q_j dz}{1 - q_j z}$$

$$= \frac{1}{d_j} d_j \tau + \frac{1}{d_j q_j} \ln(1 - q_j z) \Big|_1^{\exp\{d_j \tau\}} - \frac{1}{d_j} \ln(1 - q_j z) \Big|_1^{\exp\{d_j \tau\}}$$

$$= \tau + \frac{1}{d_j q_j} \left[ \ln(1 - q_j e^{d_j \tau}) - \ln(1 - q_j) \right] +$$

$$- \frac{1}{d_j} \left[ \ln(1 - q_j e^{d_j \tau}) - \ln(1 - q_j) \right]$$

$$= \tau + \frac{1}{d_j q_j} \ln \left( \frac{1 - q_j e^{d_j \tau}}{1 - q_j} \right) - \frac{1}{d_j} \ln \left( \frac{1 - q_j e^{d_j \tau}}{1 - q_j} \right)$$

$$= \frac{1}{d_j} \left[ d_j \tau + \left( \frac{1}{q_j} - 1 \right) \ln \left( \frac{1 - q_j e^{d_j \tau}}{1 - q_j} \right) \right]$$

$$\Rightarrow C_j = i\pi u \tau + \frac{a}{\sigma^2} \frac{d_j + b_j - i\pi \sigma}{d_j} \left[ d_j \tau + \frac{1 - q_j}{q_j} \ln \left( \frac{1 - q_j e^{d_j \tau}}{1 - q_j} \right) \right]$$

$$= i\pi u \tau + \frac{a}{\sigma^2} \left[ (d_j + b_j - i\pi \sigma) \tau + 2 \ln \left( \frac{1 - q_j e^{d_j \tau}}{1 - q_j} \right) \right]$$